

بر نام خدا

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تحکیم سری دوم سیکنالها و سیستمها

مهلت تحویل: ۱۸ اردیبهشت ۱۳۹۸



**2.3.** Consider an input  $x[n]$  and a unit impulse response  $h[n]$  given by

$$x[n] = \left(\frac{1}{2}\right)^{n-2} u[n-2],$$

$$h[n] = u[n+2].$$

Determine and plot the output  $y[n] = x[n] * h[n]$ .

Let us define the signals

$$x_1[n] = \left(\frac{1}{2}\right)^n u[n]$$

and

$$h_1[n] = u[n].$$

We note that

$$x[n] = x_1[n-2] \quad \text{and} \quad h[n] = h_1[n+2]$$

Now,

$$\begin{aligned} y[n] &= x[n] * h[n] = x_1[n-2] * h_1[n+2] \\ &= \sum_{k=-\infty}^{\infty} x_1[k-2] h_1[n-k+2] \end{aligned}$$

By replacing  $k$  with  $m+2$  in the above summation, we obtain

$$y[n] = \sum_{m=-\infty}^{\infty} x_1[m] h_1[n-m] = x_1[n] * h_1[n]$$

Using the results of Example 2.1 in the text book, we may write

$$y[n] = 2 \left[ 1 - \left(\frac{1}{2}\right)^{n+1} \right] u[n]$$

2.4. Compute and plot  $y[n] = x[n] * h[n]$ , where

$$x[n] = \begin{cases} 1, & 3 \leq n \leq 8 \\ 0, & \text{otherwise} \end{cases},$$

$$h[n] = \begin{cases} 1, & 4 \leq n \leq 15 \\ 0, & \text{otherwise} \end{cases}.$$

We know that

$$y[n] = x[n] * h[n] = \sum_{k=-\infty}^{\infty} x[k]h[n-k]$$

The signals  $x[n]$  and  $y[n]$  are as shown in Figure S2.4. From this figure, we see that the above summation reduces to

$$y[n] = x[3]h[n-3] + x[4]h[n-4] + x[5]h[n-5] + x[6]h[n-6] + x[7]h[n-7] + x[8]h[n-8]$$

This gives

$$y[n] = \begin{cases} n-6, & 7 \leq n \leq 11 \\ 6, & 12 \leq n \leq 18 \\ 24-n, & 19 \leq n \leq 23 \\ 0, & \text{otherwise} \end{cases}$$

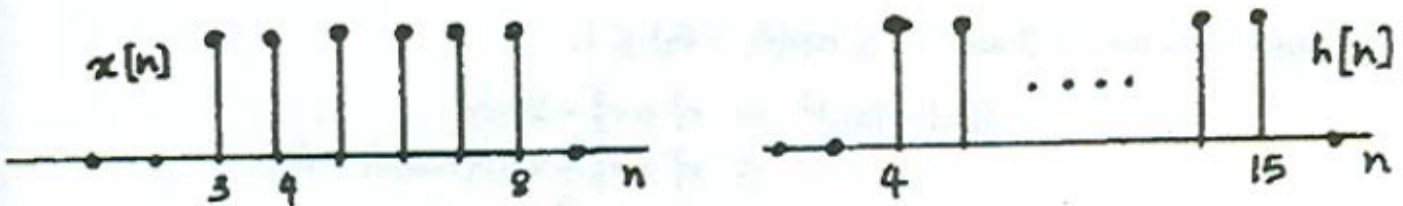


Figure S2.4

2.21. Compute the convolution  $y[n] = x[n] * h[n]$  of the following pairs of signals:

(d)  $x[n]$  and  $h[n]$  are as in Figure P2.21.

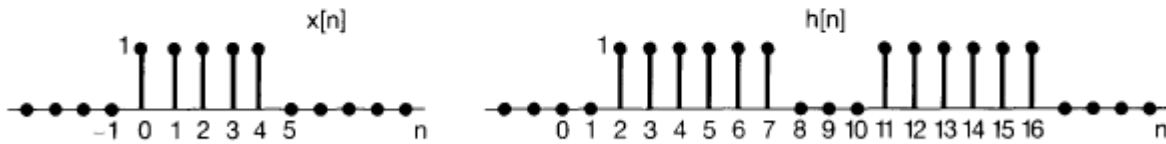
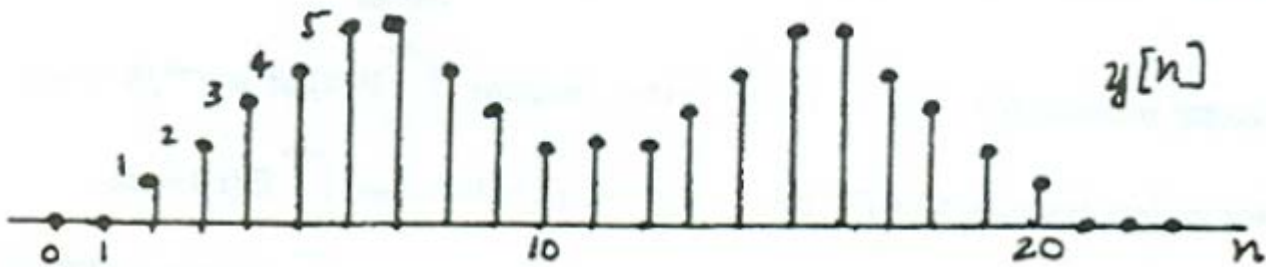


Figure P2.21

The desired convolution is

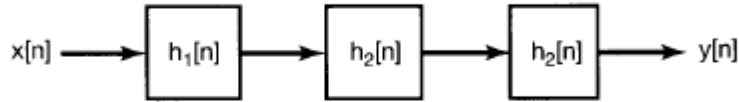
$$\begin{aligned}
 y[n] &= \sum_{k=-\infty}^{\infty} x[k]h[n-k] \\
 &= x[0]h[n] + x[1]h[n-1] + x[2]h[n-2] + x[3]h[n-3] + x[4]h[n-4] \\
 &= h[n] + h[n-1] + h[n-2] + h[n-3] + h[n-4].
 \end{aligned}$$



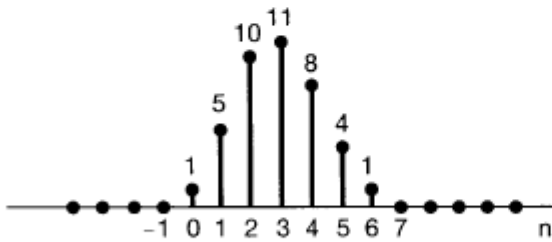
**2.24.** Consider the cascade interconnection of three causal LTI systems, illustrated in Figure P2.24(a). The impulse response  $h_2[n]$  is

$$h_2[n] = u[n] - u[n - 2],$$

and the overall impulse response is as shown in Figure P2.24(b).



(a)



(b)

**Figure P2.24**

- (a) Find the impulse response  $h_1[n]$ .  
 (b) Find the response of the overall system to the input

$$x[n] = \delta[n] - \delta[n - 1].$$

(a) We are given that  $h_2[n] = \delta[n] + \delta[n - 1]$ . Therefore,

$$h_2[n] * h_2[n] = \delta[n] + 2\delta[n - 1] + \delta[n - 2].$$

Since

$$h[n] = h_1[n] * [h_2[n] * h_2[n]],$$

we get

$$h[n] = h_1[n] + 2h_1[n-1] + h_1[n-2].$$

Therefore,

$$\begin{aligned} h[0] = h_1[0] &\Rightarrow h_1[0] = 1, \\ h[1] = h_1[1] + 2h_1[0] &\Rightarrow h_1[1] = 3, \\ h[2] = h_1[2] + 2h_1[1] + h_1[0] &\Rightarrow h_1[2] = 3, \\ h[3] = h_1[3] + 2h_1[2] + h_1[1] &\Rightarrow h_1[3] = 2, \\ h[4] = h_1[4] + 2h_1[3] + h_1[2] &\Rightarrow h_1[4] = 1, \\ h[5] = h_1[5] + 2h_1[4] + h_1[3] &\Rightarrow h_1[5] = 0. \end{aligned}$$

$h_1[n] = 0$  for  $n < 0$  and  $n \geq 5$ .

(b) In this case,

$$y[n] = x[n] * h[n] = h[n] - h[n-1].$$